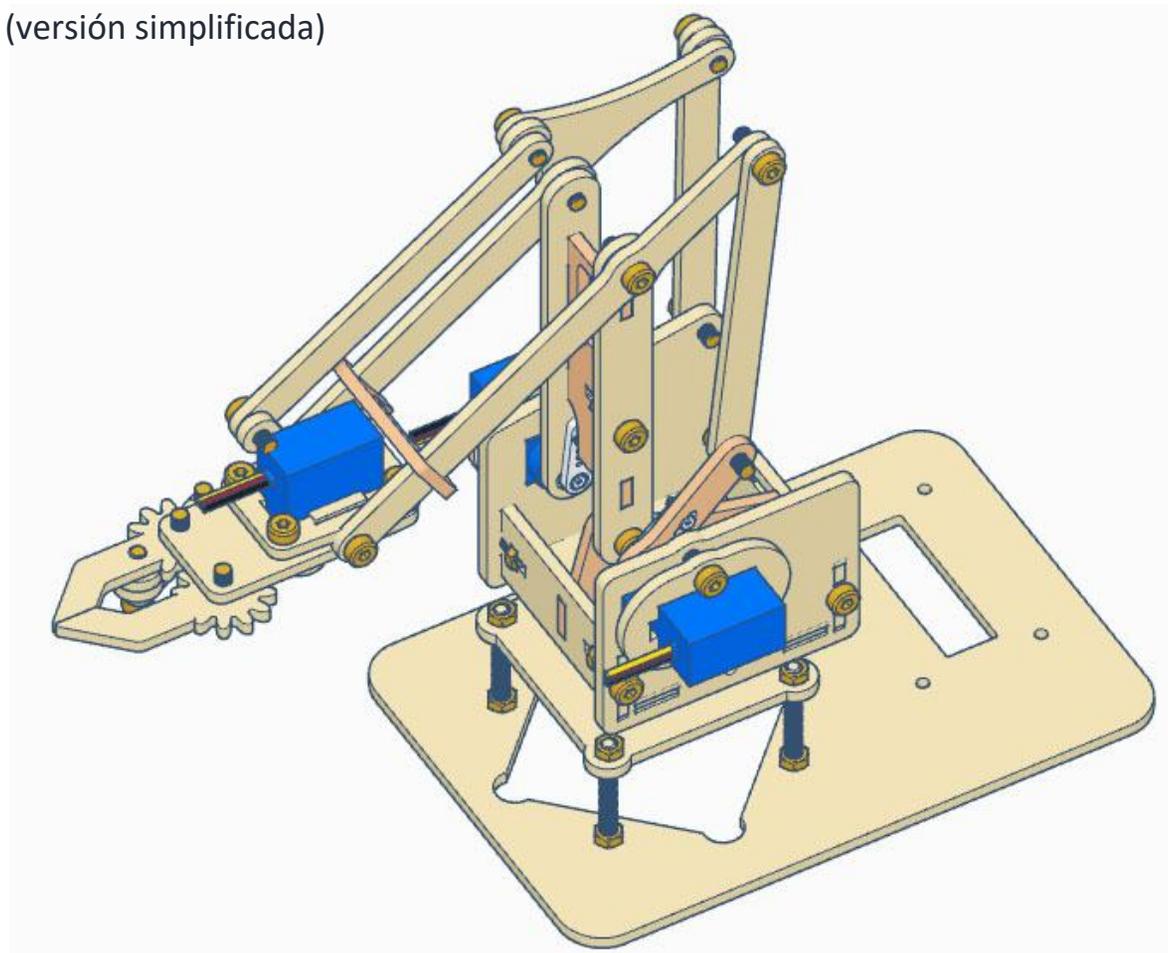


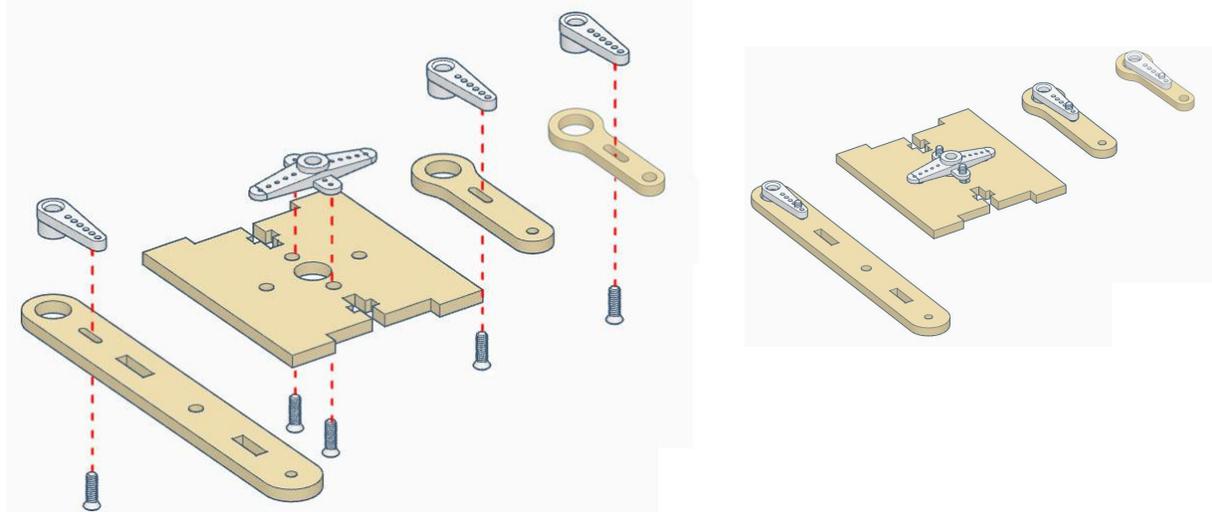
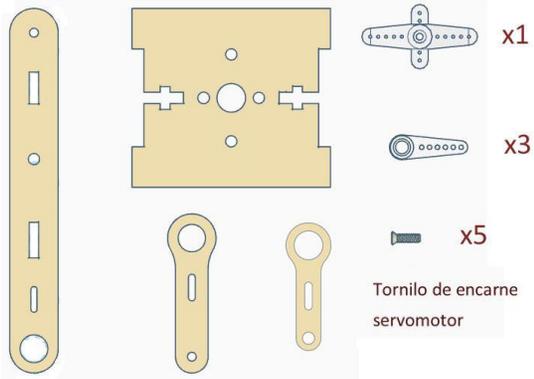
BRAZO ROBÓTICO

MANUAL DE ENSAMBLADO

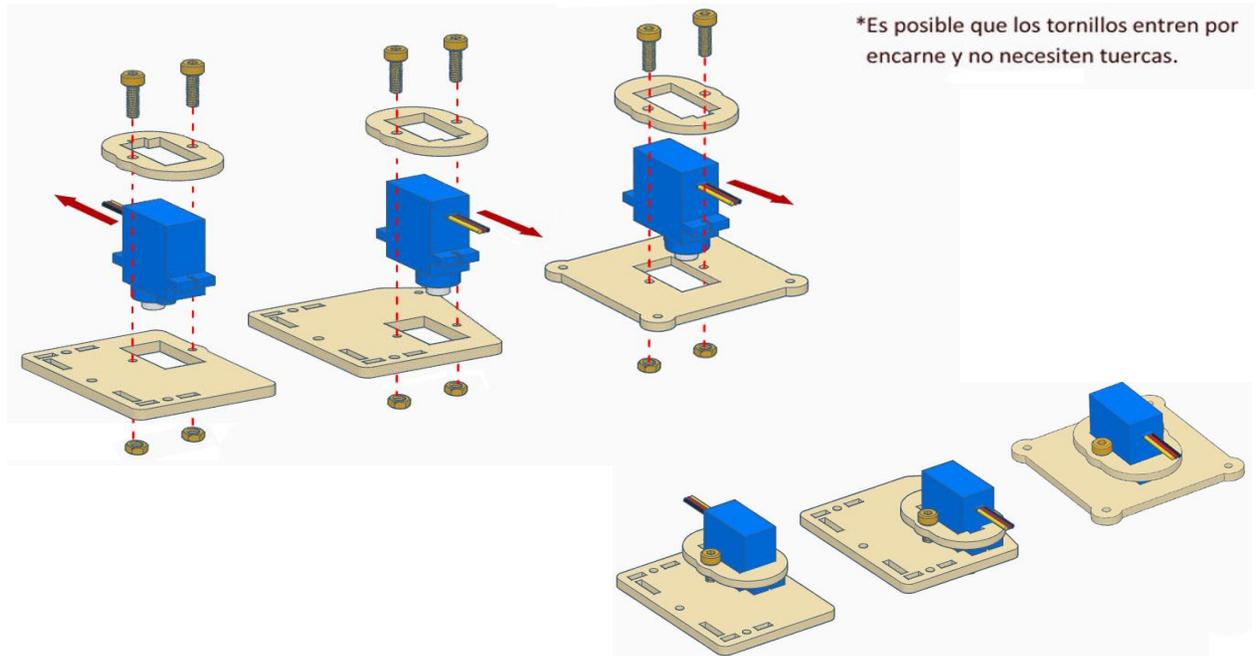
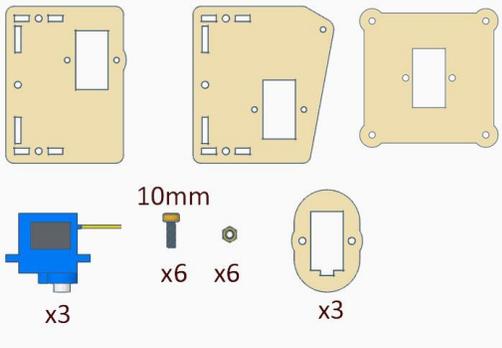
(versión simplificada)



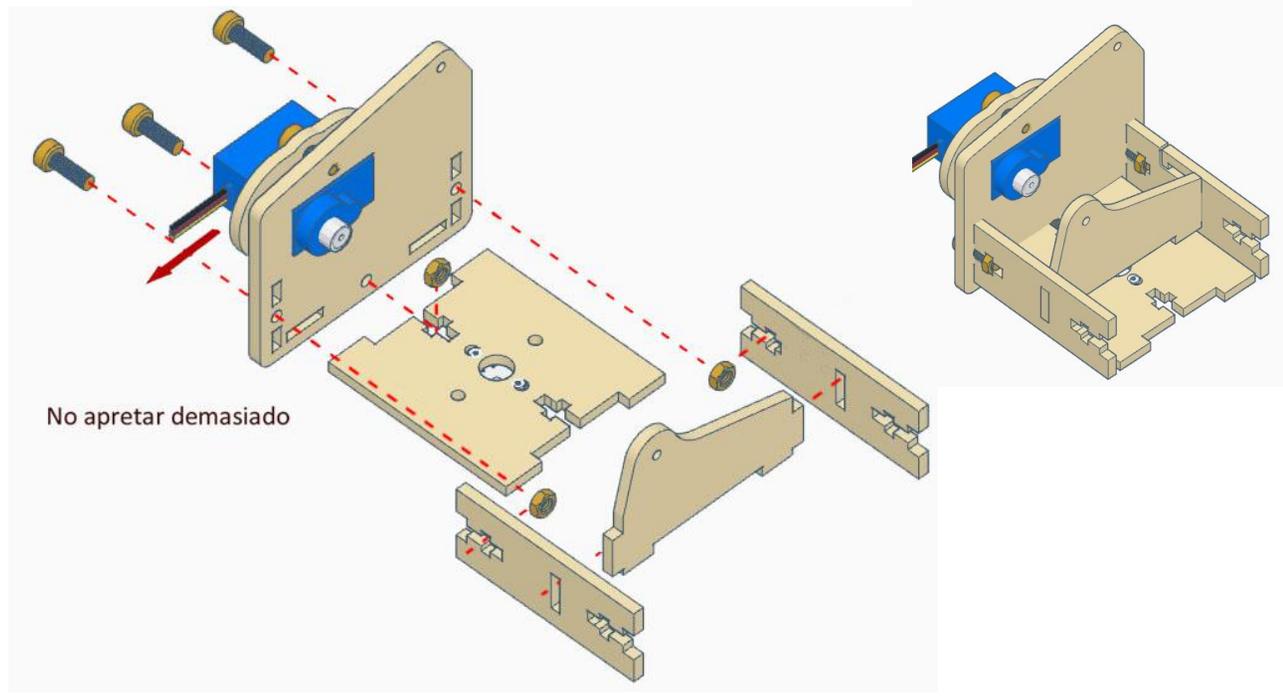
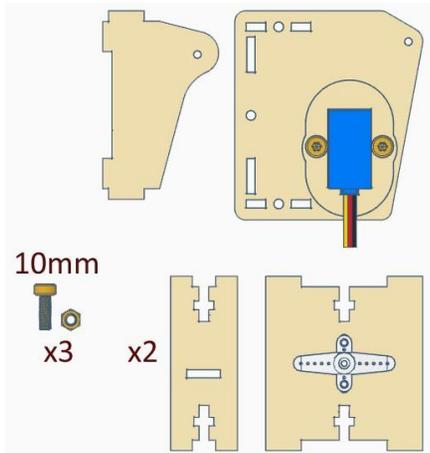
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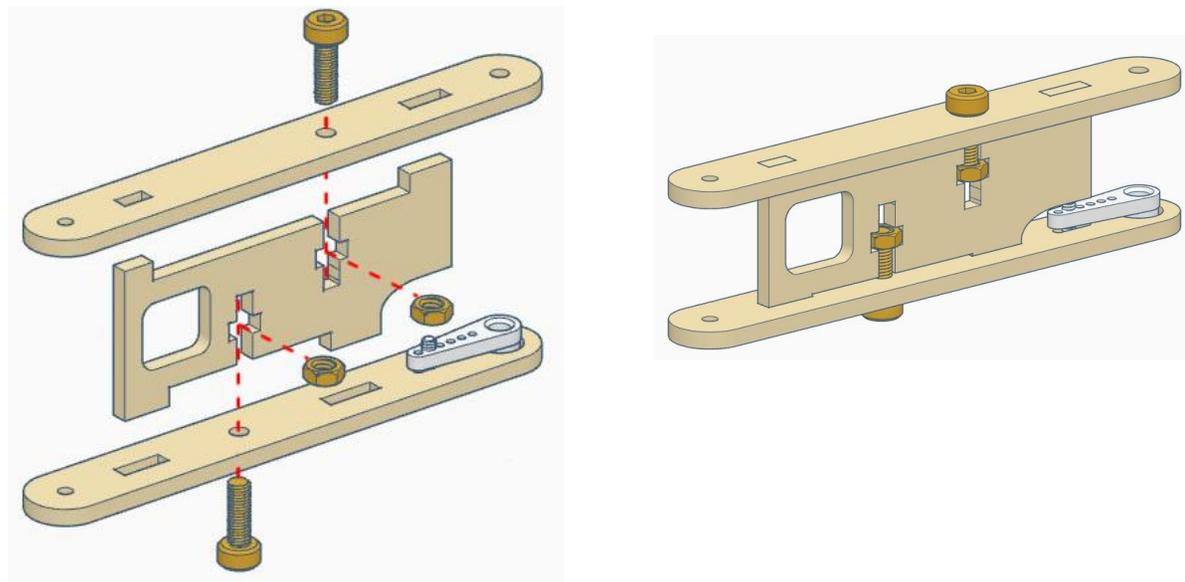
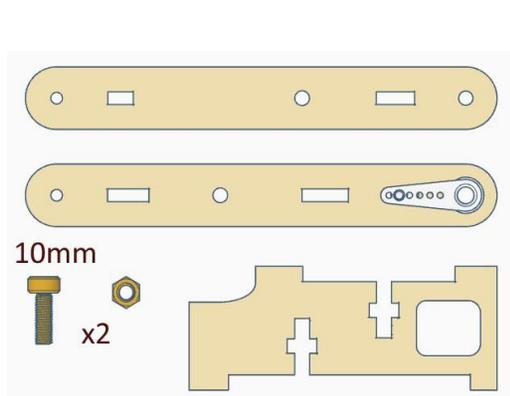
Servomotores



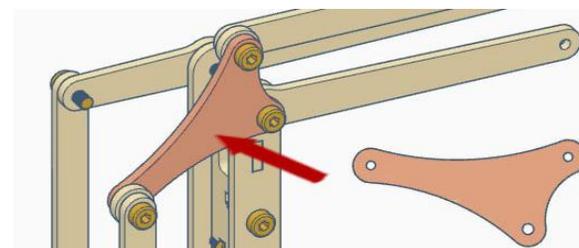
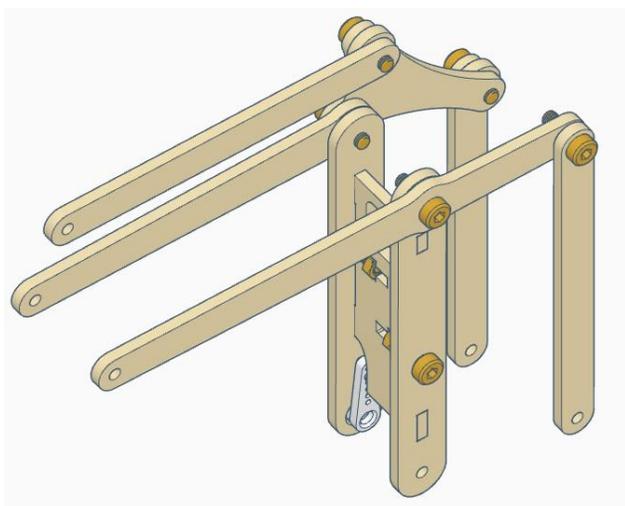
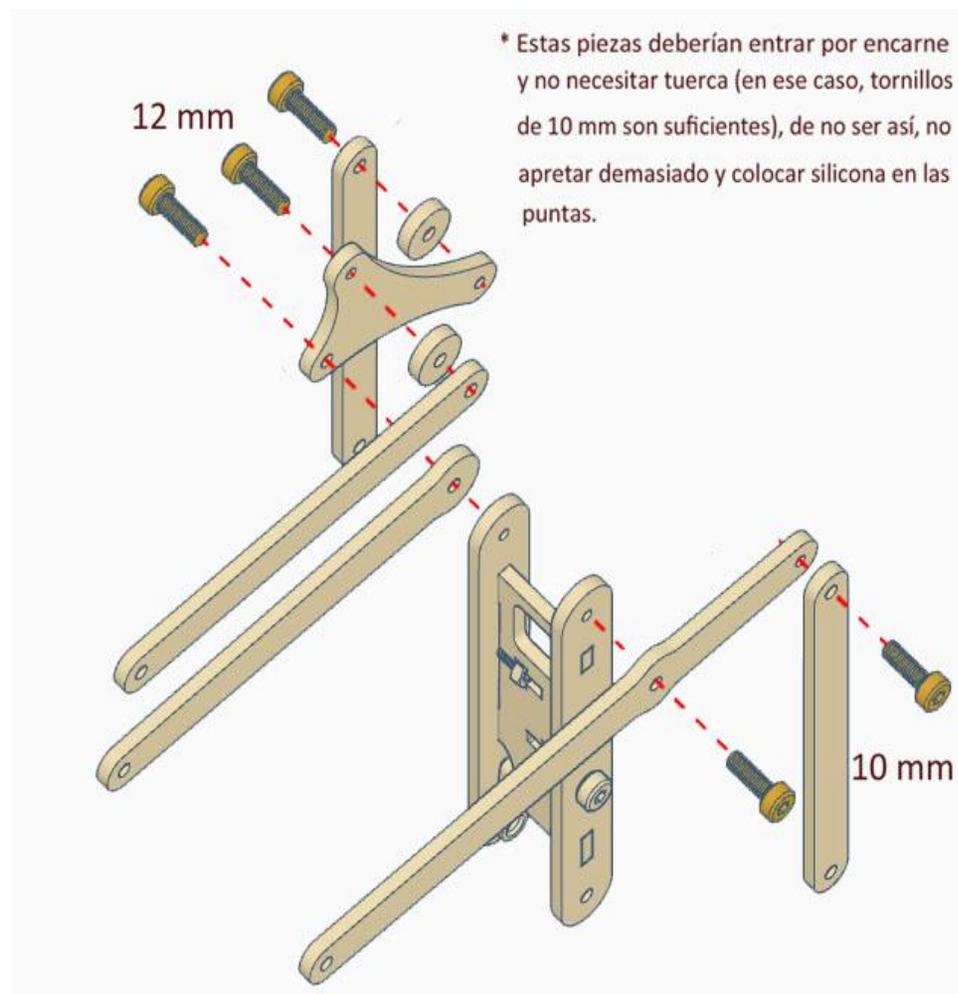
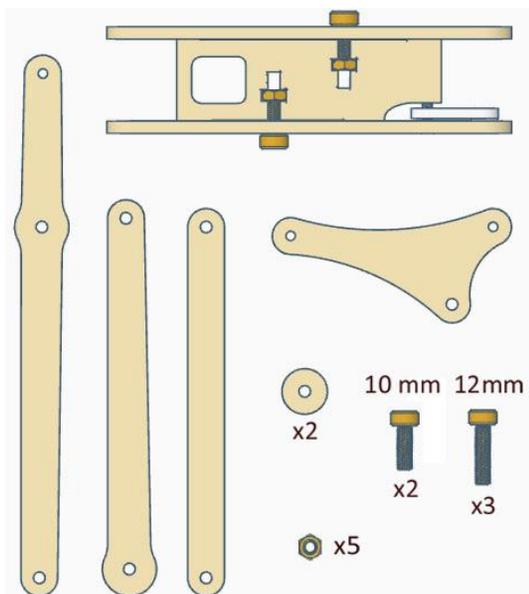
Caja (primera parte)



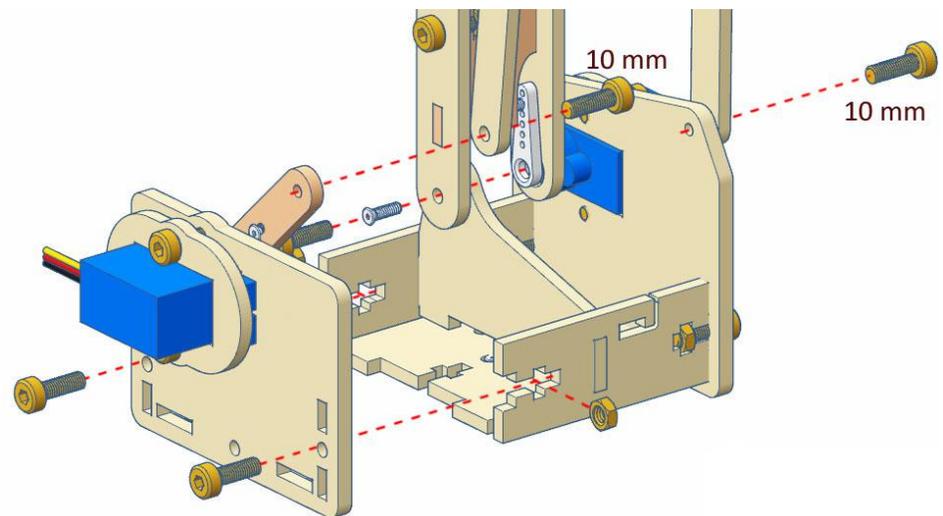
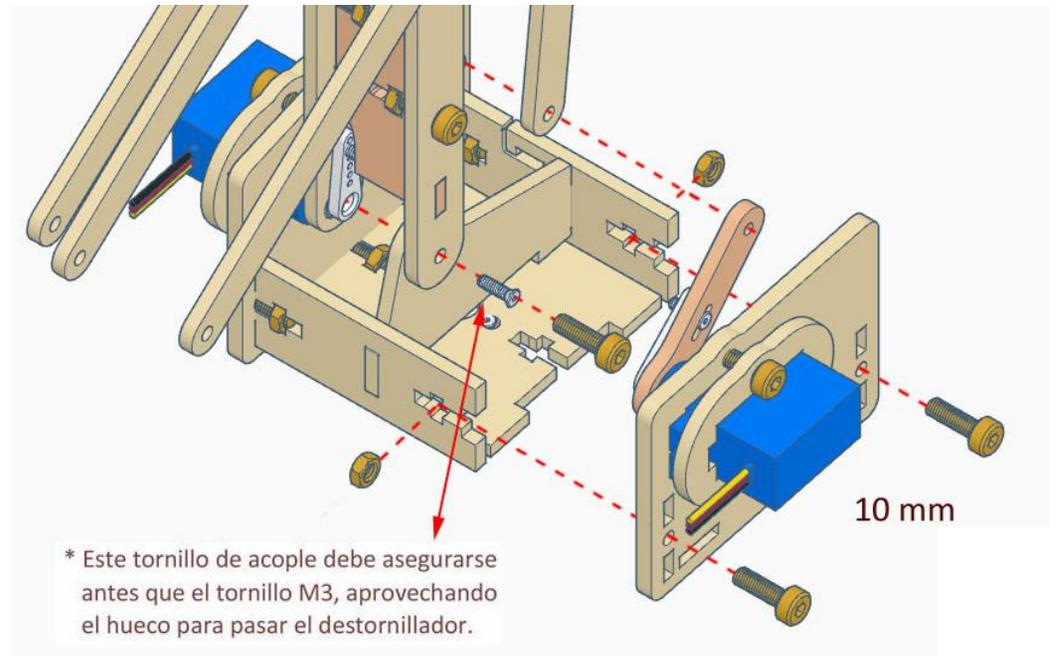
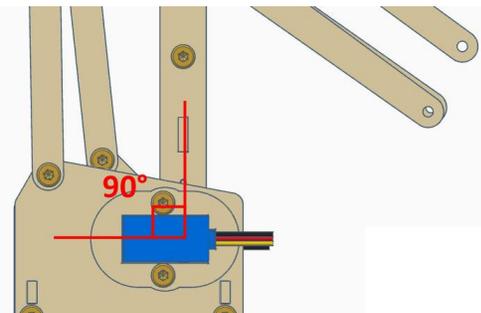
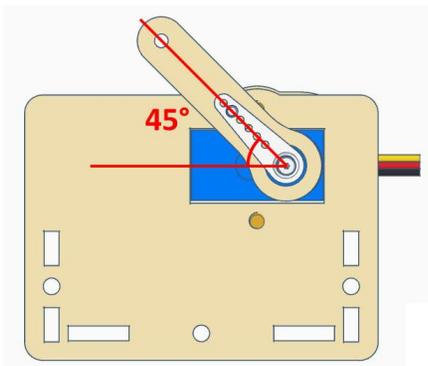
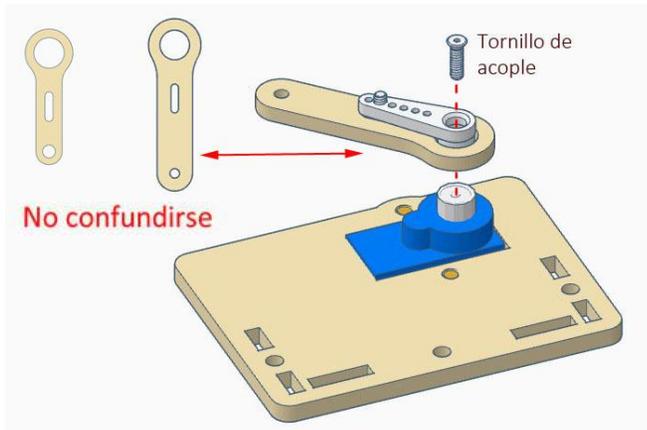
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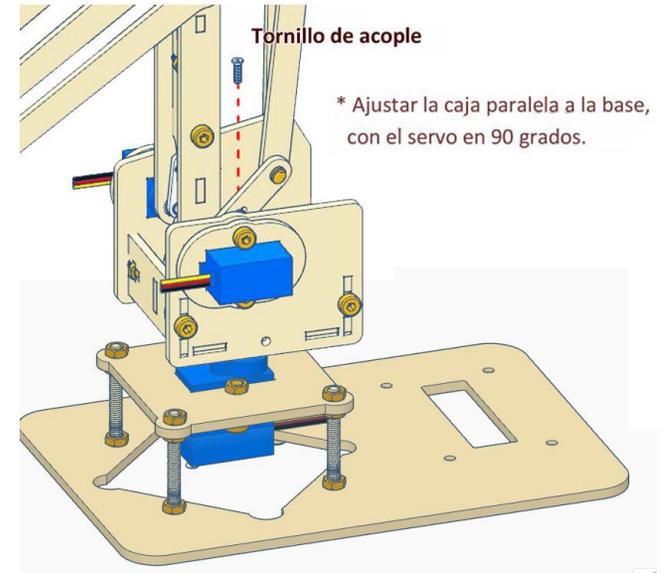
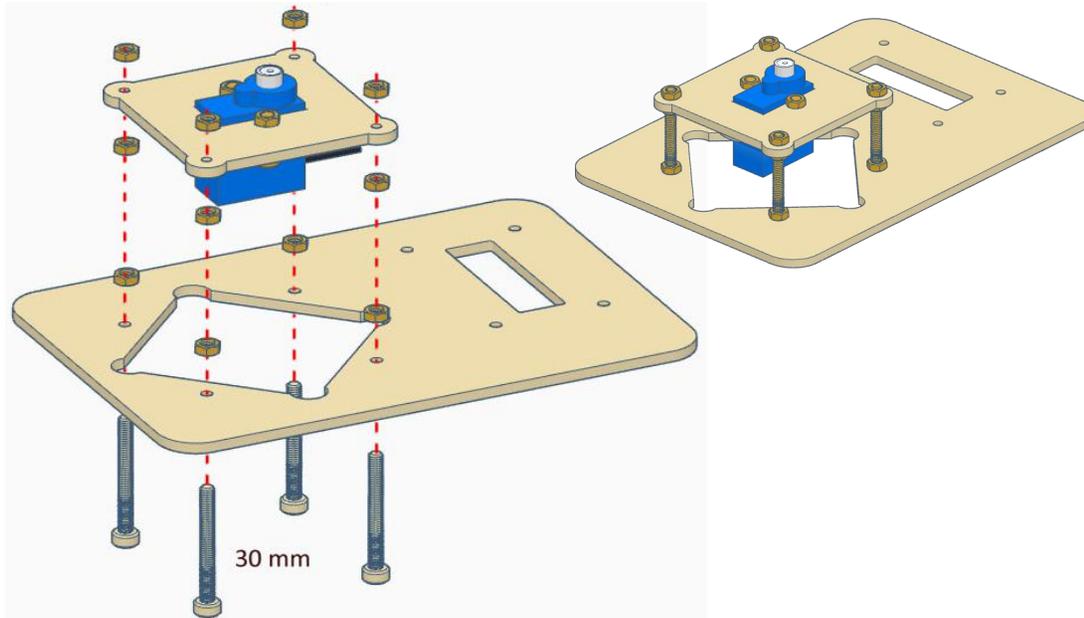
Antebrazo



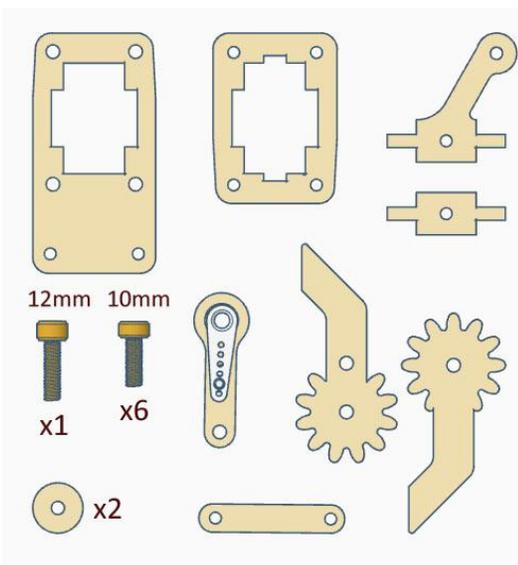
Caja (segunda parte)



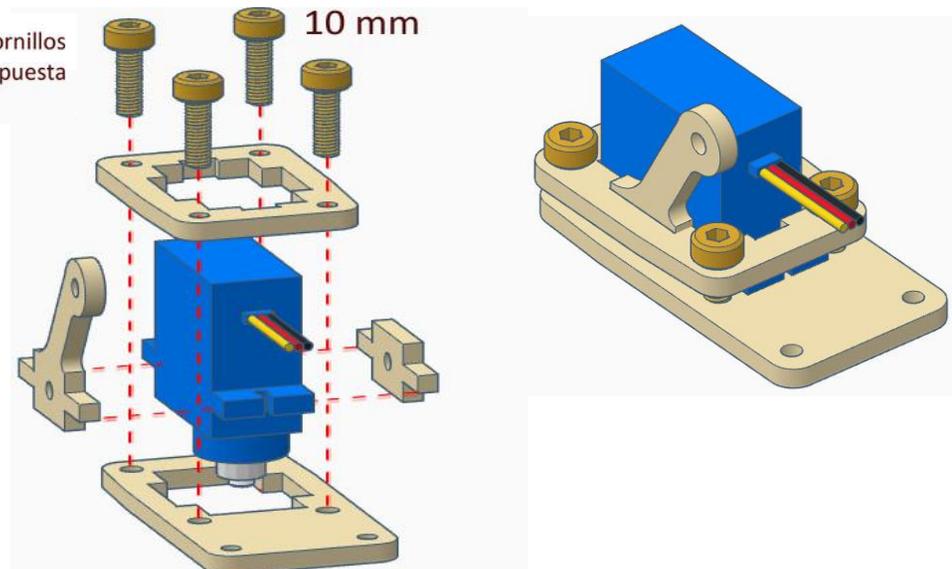
Base

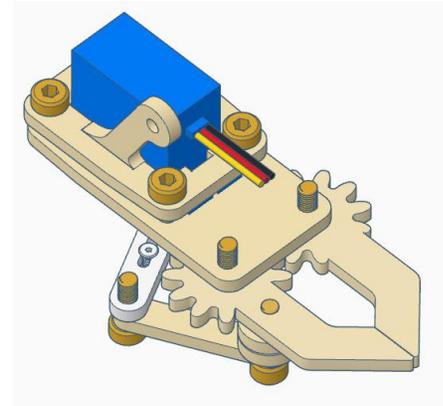
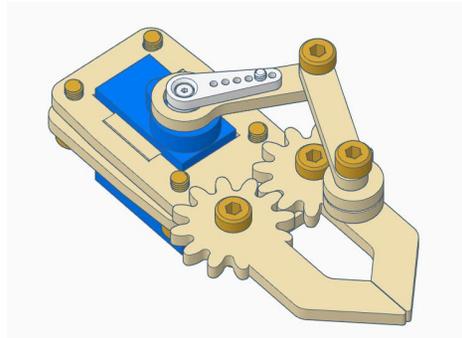
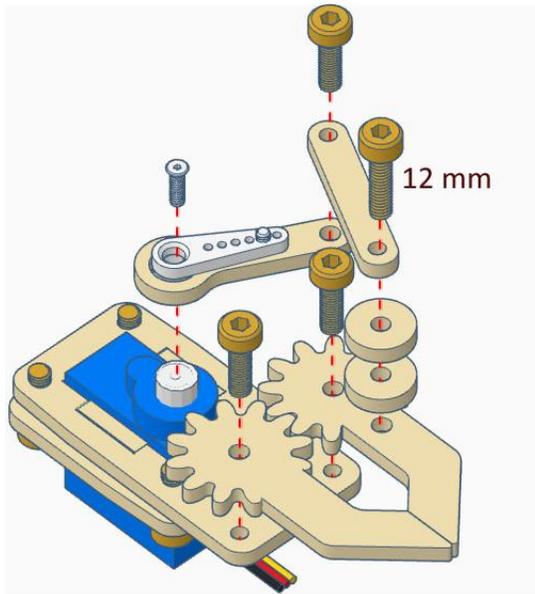


Garra



*Es posible que los tornillos entren en dirección opuesta y/o sin tuercas.





Uniendo la garra con el antebrazo (FINAL)

